

MATHEMATICAL MODELING OF OREGONATOR WITH A DIFFUSION TYPE COMMUNICATION

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We presented a mathematical model of the Belousov-Zhabotinsky reaction for Field-Noyes mechanism, which is called oregonator, taking into account the diffusion of components. A range of stoichiometric coefficient changes, which corresponds to a stationary state oregonator, is found. We study a diffusion instability and two types of unstable modes, as well as the points of oregonator bifurcation.

Keywords: *Field-Noyes model, oregonator, diffusion instability, bifurcation point.*

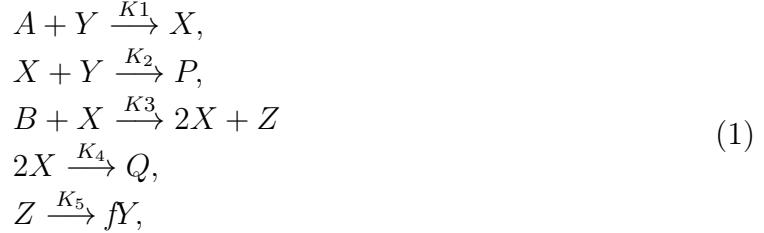
Introduction

The problem of the origin and development of the ordered structures is very important during the study of open systems, which are able to a metabolism, a change of energy and information [1 – 7]. One deal with the process of an emergence of structures and their development during a study of hydrodynamic, chemical, biochemical, biological, environmental and other non-equilibrium dissipative media [8 – 12]. In particular, the concentration structures are observed in two-dimensional reactor, where autocatalytic chemical reactions flow [8, 13, 14]. A theory of a formation of structures in molecular systems started with the work of A. Turing [15], E. Schrodinger [16], R. Glansdorff [1], B. Belousov [18], A. Jabolinsky [17, 19]. Chemical reactions give many examples of the formation of dissipative (spatial, temporal and spatio-temporal) structures. One of the first studied reactions of such type is the Belousov reaction [18]. Further studies of oscillatory chemical reactions are associated with the works of Jabolinsky [17, 19] and the emergence of the concept of "Belousov - Zhabotinsky reaction" (abbreviated as BZ). BZ reaction mechanism was developed by R.J. Field, E. Koros and R.M. Noyes [20 – 21] and formed the basis of experimental and theoretical studies of the bromat chemical oscillators. An ability of the components to diffuse is taken into account in the study of physical-chemical, biochemical, ecological systems. An existence of spatially inhomogeneous structures in nonlinear reactant systems with diffusion was first proved by A.M. Turing in 1952 [15]. Spatial structures in space of autocatalytic reaction were observed by the authors of works [13 – 14]. Accounting of a diffusion in the mechanism of these reactions extends the possibilities of mathematical modeling of real physical and chemical processes.

1. A mathematical model of oregonator

Mathematical models of autocatalytic reactions with diffusion and the results of their researches are widely used in the study of nonlinear phenomena and effects in biochemical, ecological systems, as for mathematically similar ones. Mathematical modeling of the concentration fluctuations systems was started with the work of A.J. Lotka [22 – 24]. A model known in ecology as "prey-predator" became very popular. In experimental studies, Belousov-Zhabotinsky reaction is popular [19]. A bromide bromomalonic acid-ferroin (BMF) system is one of the most successful to study the spatial structures. There

are several mathematical models of the BZ reaction, but the most famous one is the Field–Noyes version, known as Oregonator [20 – 21]:



where X is bromide acid HBrO_2 , Y is bromide Br^- , Z is Cerium IV, $A = B$ is bromate ion BrO_3^- , $P = Q$ is a concentration of products, f is a stoichiometric rate, k_i , ($i = \overline{1, 5}$) are reaction rate constants.

A system of kinetic equations by neglecting of the reverse reactions

$$\begin{aligned}
 \frac{\partial X}{\partial t} &= k_1AY - k_2XY + k_3BX - 2k_4X^2, \\
 \frac{\partial Y}{\partial t} &= -k_1AY - k_2XY + fk_5Z, \\
 \frac{\partial Z}{\partial t} &= k_3BX - k_5Z,
 \end{aligned} \tag{2}$$

corresponds to the five-step model (1).

Kinetic equations (2) based on a diffusion of components can be written as:

$$\begin{aligned}
 \frac{\partial X}{\partial t} &= k_1AY - k_2XY + k_3BX - 2k_4X^2 + D_X \frac{\partial^2 X}{\partial \xi^2}, \\
 \frac{\partial Y}{\partial t} &= -k_1AY - k_2XY + fk_5Z + D_Y \frac{\partial^2 Y}{\partial \xi^2}, \\
 \frac{\partial Z}{\partial t} &= k_3BX - k_5Z + D_Z \frac{\partial^2 Z}{\partial \xi^2},
 \end{aligned} \tag{3}$$

where t is time, ξ is spatial coordinate, D_X , D_Y , D_Z are coefficients of a diffusion of components.

2. Steady state of the system

From (2) we write the stationary model

$$\begin{aligned}
 k_1AY_0 - k_2X_0Y_0 + k_3BX_0 - 2k_4X_0^2 &= 0, \\
 -k_1AY_0 - k_2X_0Y_0 + fk_5Z_0 &= 0, \\
 k_3BX_0 - k_5Z_0 &= 0,
 \end{aligned} \tag{4}$$

and find a stationary solution X_0, Y_0, Z_0 of the system (4):

$$X_0 = \frac{1}{2} \left(\frac{k_3B(1-f)}{2k_4} - \frac{k_1A}{k_2} \right) + \left[\frac{1}{4} \left(\frac{k_3B(1-f)}{2k_4} - \frac{k_1A}{k_2} \right)^2 + \frac{k_1k_3AB(1+f)}{2k_2k_4} \right]^{1/2},$$

$$Y_0 = \frac{k_3 B(1+f)}{2k_2} - \frac{k_4}{k_2} X_0, \quad (5)$$

$$Z_0 = \frac{k_3 B}{k_5} X_0.$$

For input parameters [25]: $A = B = 6 \cdot 10^{-2}$, $k_1 = 8 \cdot 10^9$, $k_2 = 2 \cdot 10^9$, $k_3 = 2.1$, $k_4 = 4 \cdot 10^7$, $k_5 = 10^{-4}$ a range of variation of the stoichiometric coefficient is defined and positive stationary solutions X_0, Y_0, Z_0 having physical meaning are found and presented in table 1.

Table 1

Stationary solutions for different values of f			
f	$X_0, 10^{-8}$	$Y_0, 10^{-17}$	$Z_0, 10^{-15}$
0.15	0.1811	0.0071	0.2282
0.25	0.1969	0.0129	0.2481
0.35	0.2126	0.0195	0.2679
0.45	0.2284	0.0270	0.2878
0.55	0.2441	0.0352	0.3076
0.65	0.2599	0.0443	0.3274
0.75	0.2756	0.0543	0.3473
0.85	0.2914	0.0650	0.3671
0.95	0.3071	0.0766	0.3870
1.05	0.3229	0.0890	0.4068
1.15	0.3386	0.1022	0.4267
1.25	0.3544	0.1163	0.4465
1.35	0.3701	0.1312	0.4664

An increasing of a concentration of the components is observed with an increasing of the value of the stoichiometric coefficient in the system.

3. Diffusion instability

Stationary solutions X_0, Y_0, Z_0 determine the equilibrium states of the system. Assume $X = X_0 + x$, $Y = Y_0 + y$, $Z = Z_0 + z$, i.e. deviate from equilibrium, and write the system (3) in perturbations x, y, z [26]:

$$\begin{aligned} \frac{\partial x}{\partial t} &= a_1 x + a_2 y + a_3 x y + a_4 x^2 + D_x \frac{\partial^2 x}{\partial \xi^2}, \\ \frac{\partial y}{\partial t} &= b_1 y + b_2 x + b_3 z + b_4 x y + D_y \frac{\partial^2 y}{\partial \xi^2}, \\ \frac{\partial z}{\partial t} &= c_1 z + c_2 x + D_z \frac{\partial^2 z}{\partial \xi^2}. \end{aligned} \quad (6)$$

The coefficients of equations of system (6) have the form:

$$\begin{aligned}
 a_1 &= -k_2 Y_0 + k_3 B - 4k_4 X_0; \\
 a_2 &= k_1 A - k_2 X_0; a_3 = -k_2; a_4 = -2k_4; \\
 b_1 &= -k_1 A - k_2 X_0; b_2 = -k_2 Y_0; b_3 = fk_5; \\
 b_4 &= -k_2; c_1 = k_3 B; c_2 = -k_5.
 \end{aligned}$$

Consider a stability of the steady state with respect to perturbations $x_j(\xi, t) \approx \exp(k\xi - \omega t)$ and obtain the dispersion equation

$$\left| \begin{array}{ll} a_1 + i\omega - k^2 D_x & a_2 \\ b_2 & b_1 + i\omega - k^2 D_y \\ c_1 & 0 \end{array} \right| = 0$$

or correspondingly

$$\omega^3 - ip_1\omega^2 + p_2\omega - ip_3 = 0, \quad (7)$$

where $\omega = \omega_r + i\omega_i$, ω_r is a frequency, ω_i is a velocity of the perturbation growth.

The coefficients of the dispersion equation (7) have the form:

$$\begin{aligned}
 p_1 &= a_1 + b_1 + c_2 - k^2(D_x + D_y + D_z), \\
 p_2 &= (a_1 + b_1 - k^2(D_x + D_y))(c_2 - k^2D_z) + (a_1 - k^2D_x)(b_1 - k^2D_y) - a_2b_2, \\
 p_3 &= (a_1 - k^2D_x)(b_1 - k^2D_y)(c_2 - k^2D_z) + a_2b_3c_1 - a_2b_2(c_2 - k^2D_z).
 \end{aligned}$$

The results of computational experiments as part of the equation (7) by varying of diffusion coefficients showed a diffusion instability of oregonator for a range of stoichiometric coefficient $f \in (0; 1.4)$ with the values of the wave number $k \geq 0$ (Fig. 1). The criterion of oregonator instability is a condition $\omega_i \geq 0$.

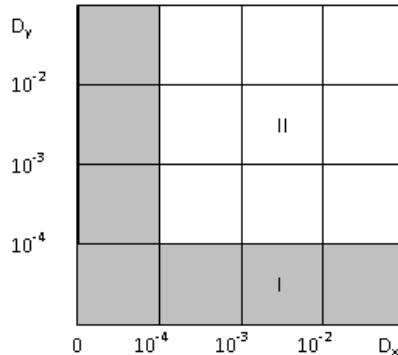


Fig. 1. Areas of oregonator instability for $f=0,7$: I – area of a stabilizing effect of diffusion; II – area of a destabilizing effect of diffusion

In areas of oregonator instability a diffusion has both stabilizing effect (Fig. 1, area I), and the destabilizing one (Fig. 1, area II). In the area of stabilizing effect of diffusion in oregonator a decrease of the velocity of perturbation growth is marked (Fig. 2, curve 1). An area of a destabilizing effect of diffusion is characterized by an increasing of a velocity of perturbation growth (Fig. 2, curve 2).

Different vibrational modes are observed for different wave numbers in oregonator (Table 2).

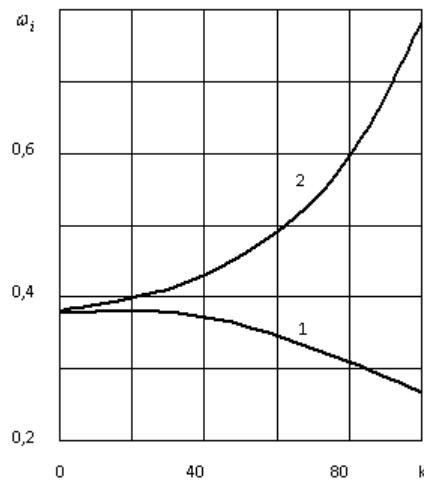


Fig. 2. The dependence of a velocity of perturbation growth on the wave number:
 1 – $D_X = 0,0001$, $D_Y = 0,002$; 2 – $D_X = 0,008$, $D_Y = 0,016$

Table 2

The values of frequency and velocity of perturbation growth for $f = 0.55$

k	$\omega_r, 10^{-8}$	ω_i
1	-0.0056	0.2910
3	0	0.3594
5	0.0777	0.4962
7	0	0.7015
9	0.0444	0.9752
11	0.0888	1.3173
13	-0.0888	1.7278
15	-0.3553	2.2068
17	-0.3997	2.7542
19	-0.0444	3.3700

The velocity of perturbation growth in Oregonator is determined by a value of the bifurcation parameter f . An instability of the system increases, when parameter f increases (Fig. 3).

A pair of numbers (k, f) , corresponding to the new state of the system, is defined as a point of bifurcation of the system. In accordance with the physical sense of the process two unstable modes should be allocated:

1. $i > 0$, $r = 0$;
2. $i > 0$, $r > 0$,

where the first mode is called a mode of stability change, and the second one –a mode of oscillatory instability.

A type of instability in oregonator changes with increasing of value f . For example, for values $f \in (0; 0,5103)$ a mode of the change of stability is observed, and for values $f \in [0,5103; 0,9914]$ a oscillatory instability mode is observed. A mode of the change of stability is characterized by velocity of perturbation growth, which is higher then for oscillatory instability mode.

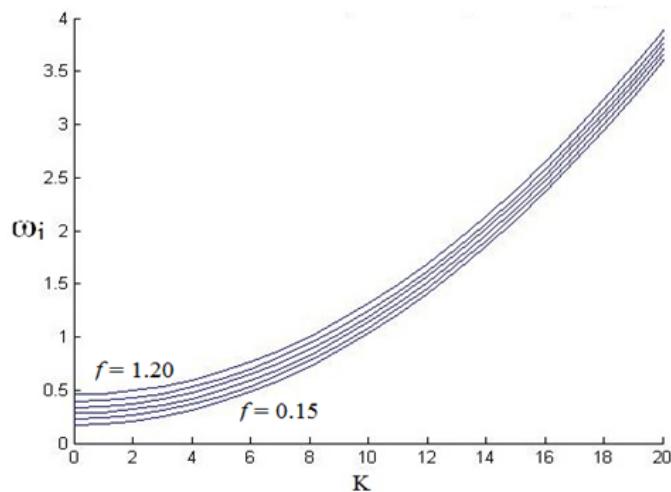


Fig. 3. Dependence of velocity of perturbation growth on the wave number for different values f

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МАТЕМАТИЧЕСКОЕ МОДЕЛИРОВАНИЕ СОСТОЯНИЯ ОРЕГОНАТОРА С ДИФФУЗИОННЫМ ТИПОМ СВЯЗИ

Л. А. Прокудина

Представлена математическая модель реакции Белоусова–Жаботинского для механизма Филда–Нойеса, называемая орегонатором, с учетом диффузии компонентов. Найден интервал изменений стехиометрического коэффициента, которому соответствует стационарное состояние орегонатора. Исследована диффузационная неустойчивость, выделены два типа неустойчивых режимов, а также точки бифуркации орегонатора.

Ключевые слова: модель Филда–Нойеса, орегонатор, диффузационная неустойчивость, точки бифуркации.

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